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Integrating reinforcement in digital fabrication with concrete: A review and classification framework

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Abstract

This article offers a comprehensive, systematic overview of the existing solutions for integrating reinforcement in digital concrete technologies with particular emphasis on Additive Manufacturing (AM) with concrete, also called 3D concrete printing (3DCP). While the functionalities of various types of reinforcement are briefly addressed, the major focus is on the integration process as such, i.e., on its technological aspects. On this basis a generic classification and process description outline has been developed for reinforcement integration, which is regarded as an extension of the RILEM process classification framework for Digital Fabrication with Concrete (DFC). In many instances, the integration occurs in a separate process step prior to or after concrete shaping. This holds true for all formative digital concrete shaping processes and for many 3DCP solutions. 3DCP approaches enable, however, integration of the reinforcement during concrete shaping as part of a single-step AM process in a simultaneous or contiguous manner, while placement of reinforcement is considered to be a sub-process.

Keywords: Digital fabrication; 3D concrete printing; additive manufacturing; reinforcement; review; classification

1. Introduction

The introduction of digital fabrication processes with concrete in a prefabrication facility or directly on the construction site is a decisive step towards the digitization of the entire value creation chain in the construction industry. Over the last five years, enormous progress has been achieved both in terms of establishing scientific fundamentals for the purposeful design of DFC processes; see, for example, [1]. And with respect to implementation of the new technologies into the practice of construction; see e.g. [2]. To date in most publications and pilot projects the greatest attention has been focused on concrete shaping processes, especially on Additive Manufacturing approaches (3DCP) while the solutions for incorporating reinforcement are still rudimentary in many instances. As such they lag the development of 3DCP technologies.

For any person familiar with concrete construction, it is clear that the use of reinforcement is mandatory in most structural applications in complying with key requirements such as load-carrying capacity, ductility, robustness, etc. While integrating reinforcement into formative digital shaping processes, one can usually reach back to established technological solutions. However, in the case of Additive Manufacturing, the challenges of introducing appropriate

46 reinforcement have already been recognised since the initial developments of 3DCP
47 technologies [3].

48 In early projects this challenge was circumvented by using 3D-printed concrete mostly as lost
49 or integrated formwork for casting, conventionally reinforced structural concrete elements; see
50 as an example [93]. Alternatively, the integration of mesh reinforcement between the layers
51 and the application of post-tensioning to the print element were demonstrated at
52 Loughborough University [94]. However, a multitude of further conceptual solutions has been
53 explored and indeed some have been implemented directly into Additive Manufacturing
54 processes. Developments are still very much ongoing. While the number of publications on
55 the topic and corresponding application examples has been increasing exponentially over the
56 last years, several review efforts have been made as well; see e.g. [4–6]. And initial
57 classification schemes have been suggested [7]. These efforts are of high value in considering
58 the wide range of options with respect to the choice of reinforcement material and geometry,
59 the orientation of reinforcement related to concrete layers and point in time related to concrete
60 deposition, the function of reinforcement, and possible technological manners of its
61 integration, etc. They provide a clearer view of the advances in the field and sharpen the
62 understanding of differences in the various approaches. However, the state of knowledge
63 covered by previous reviews and classification efforts has been in many instances overtaken
64 by the extremely dynamic developments and rapid growth in expertise and comprehension of
65 different novel technologies among the professionals involved. Hence, the authors feel the
66 need to develop a more systematic and more generic view of the subject by preparing a
67 comprehensive review and suggesting a universal classification scheme.

68 Indeed, the first purpose of the article at hand is to provide a comprehensive, critical, state-of-
69 the-art review of existing approaches to the integration of reinforcement into digital concrete
70 technologies with particular emphasis on AM/3DCP processes. When presenting the various
71 approaches, this review focuses on the technological aspects of the reinforcement integration
72 and on the process-specific characteristics such as continuity of reinforcement, formal
73 freedom, or automation capacity to name a few. In contrast, the functionality of different types
74 of reinforcement as well as structural design and aspects of design for durability are addressed
75 only briefly if at all. This is done mostly with respect to the general choice of the type of
76 reinforcement according to its overall performance. While both functionality and durability of
77 reinforcement are of major importance in structural design, these issues cannot be covered in
78 the present article due to the high complexity of the topic. Another collaborative effort will be
79 needed to offer a sound, interlinking scheme among related aspects of technological
80 implementation, as covered here, and design requirements and solutions. Indeed, this is an
81 exciting field of research and development since the optimal design solutions are likely to be
82 very technology- or application-specific, contrary to the “one-size-fits-all” strategy of
83 reinforcement bars in cast concrete.

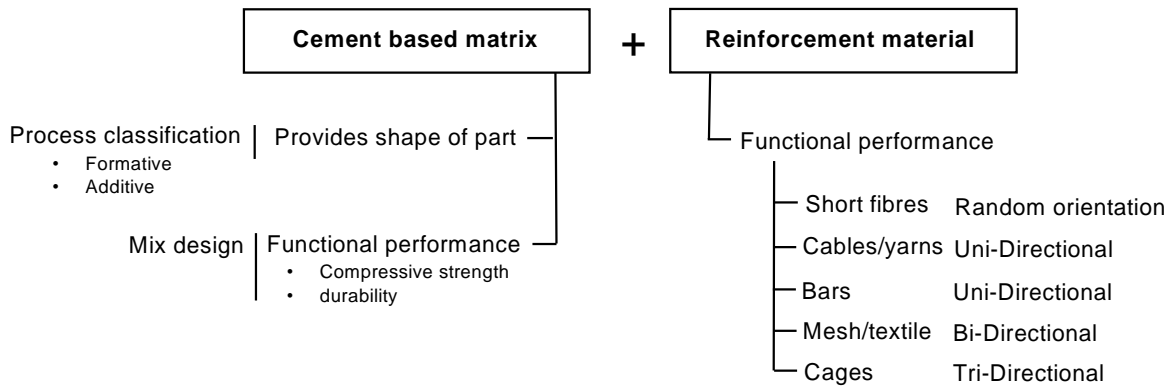
84 Based on the analysis of the state-of-the-art as presented in the review and numerous
85 comprehensive discussions among the authors, a generic, technology-oriented classification
86 for integrating reinforcement into digital fabrication with concrete is suggested. The benefits of
87 establishing such classification are obvious since it provides a basis for a) a clear, systematic
88 description of processes and process chains, b) seamless communication between
89 stakeholders in a highly interdisciplinary field, and c) comparative analysis of various
90 approaches. Furthermore, comprehensive classification is essential in developing application
91 guidelines and other technical or regulatory documentation as well as a reference for further
92 purposeful advancements in DFC technologies. While developing the classification the
93 authors did their best to follow both the spirit, systematic, and terminology of the RILEM

94 process classification framework for DFC prepared by the RILEM Technical Committee 276-
 95 DFC “Digital fabrication with cement-based materials”.

96 **2. State-of-the-art review**

97 **2.1 Review concept**

98 For most applications of concrete parts, elements, and structures reinforcement is
 99 indispensable in attaining the required mechanical performance. While key features of
 100 concrete with respect to its use in construction are compressive strength and durability, the
 101 main functions of reinforcing material are to carry tensile forces and to impart structural
 102 ductility. The various reinforcements differ in terms of their capacity to carry tensile forces and
 103 their direction of action; see Figure 1. Certainly as the most widely used composite material
 104 there is more to say about the features and functionalities of reinforced concrete, i.e., about
 105 both structural and reinforcing materials’ obvious, very successful performance together.
 106 However, the focus of this review is on digital fabrication processes with concrete. From this
 107 technological perspective in the overwhelming majority of existing approaches and
 108 applications, concrete processes provide for the shape of a manufactured element
 109 independently if a formative shaping process such as casting or additive shaping process like,
 110 e.g., material extrusion is used. Only in rare cases does the arrangement of reinforcement
 111 create scaffolding for concrete deposition and “dictate” the shape of the element. Thus, the
 112 key question with respect to manufacturing with reinforced concrete is how to integrate
 113 reinforcement into concrete with minimum interference in the concrete shaping process.



114 **Figure 1.** Reinforced concrete as composite material with the assigned main functionalities
 115 of the two components concrete and reinforcement.
 116
 117

118 This section provides an overview of different reinforcement integration approaches used in
 119 the context of extrusion-based and jetting-based 3D concrete printing technologies. Particle
 120 bed printing techniques are not explicitly considered in this review for three reasons: 1) at this
 121 stage this technique is applied very seldom at the common scale of concrete elements, 2) no
 122 reinforcement approaches requiring special attention exist specific only to this AM method, 3)
 123 the authors want this review to be concise and readily comprehensible.

124 The review is organised by reinforcement type: bars, grids/meshes, cages, textiles, cables,
 125 nails, and short fibres. A further differentiation occurs according to the reinforcing material:
 126 steel, carbon, glass fibre, etc. Rather than being exhaustive, representative examples are
 127 selected with the intention of covering all known relevant approaches. Section 2.2 briefly
 128 describes structural functions and process-specific characteristics to show the perspectives of
 129 both design and technology. The review of the existing approaches for integration of
 130 reinforcement in the context of Additive Manufacturing with concrete is presented in Section
 131 2.3, while some general conclusions are given in Section 2.4.

132

133 **2.2 Structural functions and process-specific characteristics of reinforcement**
134 **integration in 3D-concrete-printing**

135 **2.2.1 Structural functions**

136 Not every type of traditional reinforcement integration in 3D-concrete-printing can be used for
137 static-constructive purposes. In this respect material characteristics, geometric dimensions,
138 installation position, the bond with concrete, durability, etc. are decisive. When using steel it
139 is possible to fall back on well-established material parameters. The material characteristics
140 of yarns and textiles made of carbon, glass or basalt fibres are subject to greater scattering
141 as these are composites whose behaviour depends on the materials used for impregnation;
142 see e.g. [95]. Furthermore, the bond between the reinforcement and the concrete matrix is
143 crucial to the effectiveness of the reinforcement. The bond is significantly influenced by the
144 form fit using the surface condition of the reinforcement and its complete embedding into the
145 matrix.

146 By using different types of reinforcement, the failure form of the components can be
147 influenced. However, while the failure behaviour of reinforcement ranges from brittle, abrupt
148 failure as, for example, in the case of carbon reinforcements, to good-natured, slow-onset
149 failure as with steel reinforcements. Failure on the composite and component levels is affected
150 by a number of additional parameters such as the degree of reinforcement and the geometry
151 of the component. The ductility of components can be increased by the additional use of short
152 fibre reinforcement.

153 **2.2.2 Process-specific characteristics**

154 While the structural functionalities of reinforcement are critical to structural design, they are
155 indirectly relevant also in manufacturing processes. The choice of material and the position of
156 reinforcement in an element to be printed certainly affects possible integration scenarios for
157 reinforcement and associated process characteristics. Establishing the links between
158 structural design and technological implementation is certainly essential from a general
159 perspective. However, detailed deliberations are beyond the scope of this paper. Thus, the
160 process characteristics are presented predominantly from the technological perspective.

161 **• Continuity of reinforcement**

162 The continuity of the reinforcing entities is of elementary importance to the global load-
163 bearing capacity of a structural element or of an entire structure. In particular, achieving
164 continuity of reinforcement either orthogonal or inclined to the deposited concrete
165 layers represents a major challenge. Reinforcement strategies offering such
166 reinforcement arrangements can – in addition to providing the necessary vertical
167 reinforcement – also improve cross-layer force transfer and so make for less
168 anisotropic mechanical behaviour.

169 **• Automation capability**

170 Starting from the automation of the concrete shaping process, the automation of
171 reinforcement integration is essential to the enabling of seamless digital fabrication in
172 the future. To arrange the respective reinforcement elements in an automated process,
173 the automation capability assesses the process engineering effort required. The
174 automation of approaches in a single process step together with the shaping of the
175 concrete seems particularly demanding.

176 **• Geometric freedom**

177 The geometric freedom that additive concrete application allows can be limited by the
178 choice of reinforcement technique. Thus, the technology of reinforcement integration
179 exhibits some restrictions with respect to both structural and architectural design.

- 180
- 181 • **Process speed**
182 An important criterion both for the technical applicability and economic viability of any
183 reinforcement technique is the achievable process speed. This is particularly relevant
184 for single step processes in which reinforcement is introduced simultaneously or
185 congruously to the shaping of the concrete. In such cases an insufficient process
186 speed or insufficient ease of the process – both together defining the overall process
187 speed – can delay the concrete printing process, possibly leading to long time intervals
188 between subsequent layers, which may result in insufficient interlayer bonds, generally
189 leading to an undesired slowdown of the entire AM process. However, also in two-step
190 processes, i.e., where the reinforcing process is decoupled from the concrete shaping,
191 the production efficiency is of high relevance.
 - 192 • **Robustness of the process**
193 Various approaches to reinforcement implementation impose various levels of
194 technical sophistication when being implemented. Generally, the robustness of a
195 process tends to decrease with an increasing level of complexity, e.g., the number of
196 necessary process sub-steps or high requirement on precision in timing or positioning.
197 Some types of reinforcement require additional installation aids during their integration.
198 These temporarily used devices increase the complexity of automation and in turn
199 have an influence on the robustness of the entire process, increasing the infrastructural
200 requirements. Additionally, the robustness of the reinforcement material as such plays
201 a role with respect to range of its handling scenarios.
 - 202 • **Technological maturity level**
203 The technological maturity level is not really a process-specific characteristic, but
204 rather the indicator of the current state of development for the given reinforcement
205 type. This indicator is supposed to express the effort required to implement a new
206 technology successfully, here a reinforcement approach. The assessment is based on
207 the so-called Technology Readiness Level (TRL), which is defined in nine levels and
208 ranges from “the observation and description of the functional principle” to “a qualified
system with proof of successful use”; see, for example, [96].

209 Indeed, the quantification or at least comprehensive qualitative description of the process
210 specific characteristics listed above are crucial for a comparative assessment of various
211 approaches to incorporating reinforcement into digital fabrication with concrete. In the
212 following review, however, the authors will not be particular in respect of these characteristics
213 due to the very limited amount of available qualitative and quantitative information as yet.

214 **2.3 Review of representative reinforcement concepts**

215 **2.3.1 Bars**

216 Reinforcing concrete structures with conventional reinforcing bars is a standard method in
217 construction. Not surprisingly this method is also being investigated for its applicability in
218 Additive Manufacturing with concrete. The known concepts range from the placement of
219 straight and pre-bent reinforcing bars in-between the printed layers, through techniques
220 specifically developed for reinforcing also in the vertical direction, up to the drop by drop
221 welding of individualised reinforcing bars using Wire Arc Additive Manufacturing (WAAM)
222 processes; see Figure 2.



Figure 2. Reinforcement strategies using steel bars: a) placement of straight reinforcement bars in the print plane [8]; b) placement of reinforcement in horizontal as well as in vertical direction [9]; c) 3D-printed reinforcement bars using WAAM welding process [10].

In order to reinforce straight, 3D-printed walls, unbent reinforcing bars can be placed into the still fresh concrete parallel to the printing plane and then covered by a subsequent layer of concrete; see Figure a. This approach was, for example, demonstrated by [8] and the bond between reinforcement and concrete was analysed by [11]. For more complex geometries such as the Cohesion Pavilion at the University of Innsbruck [12], the reinforcing bars have to be pre-bent manually or automatically and positioned in the correct location between the layers, as was done in most of the 47 different parts that comprise the structure. Often this also required adapting the internal concrete filament structure to match the limited geometrical flexibility of the pre-bent bars.

The challenge of integrating reinforcement bars in both directions was tackled in a demonstrator from the TU Braunschweig using the Shotcrete 3D Printing technology [13]. For this purpose, a process-specific printing strategy involving a sequence of manufacturing steps was developed. In the beginning the input geometry is parametrically converted to contain slight horizontal undulations, which are later used to integrate the vertical reinforcement. Every 50 cm the printing process is stopped and pre-bent reinforcing elements are placed on the top layer. The undulations thus create tabs over the entire height of the wall, into which the unbent vertical reinforcement can be inserted; see Figure b. The now still external reinforcement is covered by another layer of shotcrete and subsequently trowelled under automation [9].

In the projects described above, the reinforcing bars were placed manually. In order to improve the accuracy of the positioning, the applicability of Augmented Reality was tested in the last example. An automation of the placement process is also possible, although with increasing bar lengths it is more challenging due to the long bars' sensitivity to vibration.

The possibility of avoiding some of the challenges mentioned above, i.e., pre-bending, two-way reinforcement, and automated placement, 3D printing using a parallel to the printing plane was suggested by Mechtcherine *et al.* [10] using Wire Arc Additive Manufacturing (WAAM); see Figure 2c. In the WAAM method, the reinforcing elements are built up in a drop-wise manner enabling a maximum of geometric flexibility, including the possibility of thickening the printed bars locally, so resulting in an improved bond between concrete and reinforcement. Tensile tests confirmed load-bearing behaviour comparable to conventional concrete steels as well as a ductile failure of the bars [10]. Hurdles in applying this concept are that: 1) the steel printing process is slower than the concrete printing process; 2) the steel printing generates very high temperatures, which could potentially damage the concrete, and 3) the WAAM welding process is so costly. The applicability of this process to digital fabrication with concrete is currently being investigated by several research groups [10,14,15].

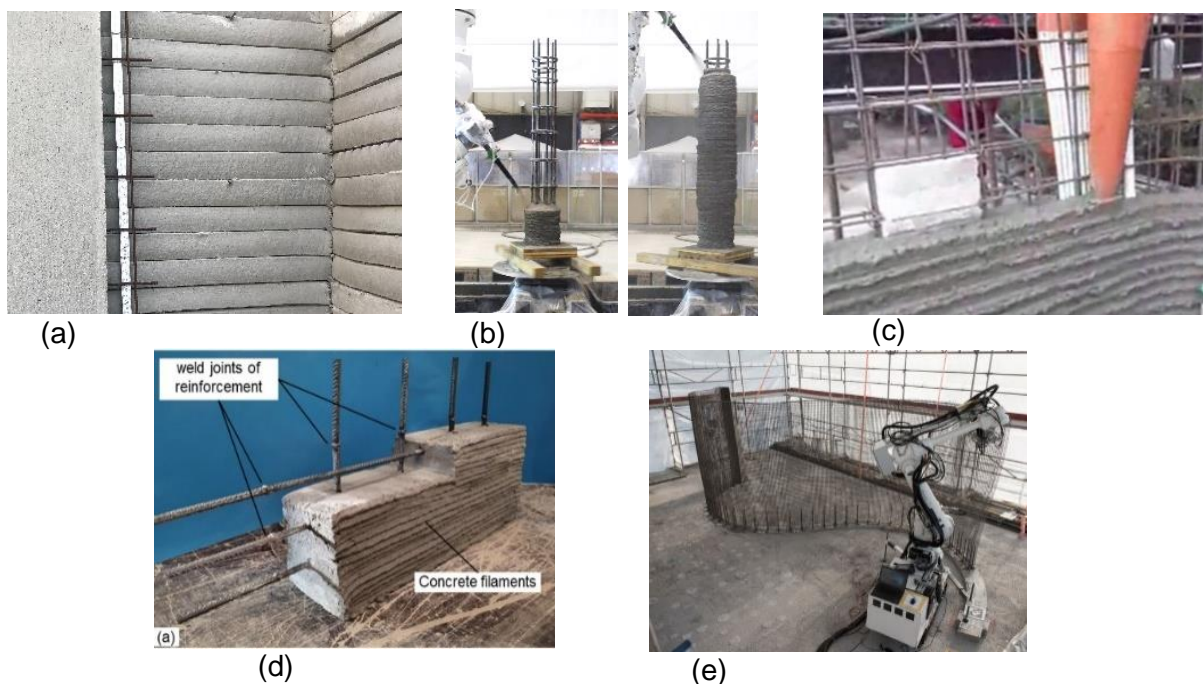
2.3.2 Grids, mats and cages

Today reinforcement meshes are manufactured mostly of steel but in some cases from polymers reinforced with glass or carbon fibre as well. Mats are also used as semi-finished

265 products to produce more complex reinforcing cages [16]. To cover a wide range of different
 266 stresses, reinforcing meshes are produced with different bar thicknesses and mesh sizes.
 267 Prefabricated meshes reduce the amount of work on the construction site, as individual bars
 268 no longer have to be laid out and connected. The use of prefabricated meshes and
 269 reinforcement cages in digital fabrication with concrete offers the advantage that the
 270 reinforcement is already arranged in two principal directions. However, approaches in
 271 assembling the meshes or cages automatically on site have been developed as well. Thus,
 272 different concepts for integrating mats and cages into the digital concrete technologies
 273 concentrate either on the challenges related to shaping the reinforcing meshes into the desired
 274 geometry, on the shaping of concrete for given mesh geometry, or sometimes on both cases.

275 2.3.2.1 Metallic grids, mats and cages

276 The most straightforward way of reinforcing 3D-printed concrete structures using steel mats
 277 was demonstrated at the TU Dresden. The wall shown in Figure 3a was printed as a monolithic
 278 structure using a nozzle with a width equal to the width of the wall, here 150 mm. Short steel
 279 bars were placed every couple of concrete layers perpendicular to the wall plane, so that their
 280 ends protruded from concrete. After concrete hardening, the steel grid was installed on the
 281 wall surface using protruding bars' ends as supports; see Figure 3a [17]. After that, the mesh
 282 was covered with a protective layer of concrete.



283
 284 **Figure 3.** Integration of steel mats and cages: a) steel grid installed on a 3D-printed wall after
 285 concrete hardening [17], b) Shotcrete 3D Printing around a preplaced reinforcement cage [18];
 286 c) in-situ printing encasing a preplaced reinforcement mat using a split nozzle [19]; d) mesh
 287 created from welding short bars onto each other using a stud-welding process [20]; e) robotic
 288 in-situ fabrication of a double curved reinforcement cage [21].
 289

290 In contrast to that, application of concrete on pre-configured and preplaced reinforcement
 291 cages using Shotcrete 3D Printing was developed at TU Braunschweig. In the experiment
 292 depicted in Figure 3b, a standard reinforcement cage for a column was placed on a computer-
 293 controlled turntable before Shotcrete 3D Printing was performed. A section through the column
 294 showed a good embedment of the reinforcement in the concrete without visible inclusion of
 295 air voids [18].

296 The Chinese construction company Huashang Tengda developed and patented a process for
297 integrating preplaced conventional steel reinforcement meshes in the 3D printing process
298 based on layered extrusion by encasing them with concrete one layer after another. The
299 concrete is deposited from two sides around reinforcement using a split nozzle as shown in
300 Figure 3c. The split-nozzle is capable of printing around meshes of about 1.5 m height [19].
301 To produce walls at full room height, a second or possibly third series of mats with appropriate
302 overlap, have to be mounted as the concrete printing progresses.
303 While the reinforcement described in the examples above was manually pre-configured and
304 pre-placed in position, there are attempts to automate these processes and integrate them
305 into the printing process. In a concept from RWTH Aachen and KU Leuven, the fabrication of
306 a freeform mesh structure and the printing of concrete around this structure are envisioned to
307 take place simultaneously. The fabrication of the mesh is based on a stud welding process in
308 which pre-cut reinforcement bars of 8 mm in diameter and approximately 25 cm in length are
309 butt-welded in both the horizontal and vertical directions. In the demonstrator depicted in
310 Figure 3d, however, the mesh was welded manually [20]. Concrete was printed around the
311 structure using a split nozzle, generally similar to the process depicted in Figure 3c, however,
312 with the advantage that the nozzle does not require the excessive height of the technology in
313 which preinstalled meshes are used. For a distance between the nozzles of 1.5 times the
314 reinforcement diameters, good inclusion of the rebar was observed. However, the small
315 leeway made the process prone to collisions of the nozzle with the reinforcement.
316 The Mesh Mould process, developed by researchers of ETH Zurich, involves the bending and
317 welding of 6 mm steel reinforcement by a mobile robot *in situ* for creating geometrically
318 complex reinforcement structures; see Figure 3e. After the entire mesh structure has been
319 fabricated, it is filled with concrete in more or less conventional fashion. In the demonstrator
320 at the DFAB HOUSE on NEST, this was done by laterally pumping concrete into the mesh
321 [21]. Automated concreting, similar to the extrusion-based approaches followed by Huashang
322 Tegna or the Shotcrete 3D Printing, seem to be feasible in future applications in conjunction
323 with the automated fabrication of reinforcement cages.
324 The examples given indicate the potential of the combination of automated grid production
325 and automated concrete application, but due to the high complexity of such combination, full
326 automation has not yet been proven.

327 **2.3.2.2 Carbon grids and mats**

328 Due to their higher flexibility in comparison to steel mats and their narrower mesh size, the
329 suitability of carbon fibre mats for additive manufacturing with concrete is being presently
330 investigated in several research projects. In these experiments different methods of
331 concreting, i.e., by extrusion and spraying, as well as different sequences of concrete
332 placement, i.e., before or after placing the mat, have been investigated.
333 One way of reinforcing construction elements is to press a carbon fibre mat into the still fresh
334 concrete, directly after the core has been printed. This approach was demonstrated using
335 Shotcrete 3D Printing in [22]. Subsequently the core and the mesh are covered with another
336 layer of concrete; see Figure 4a. This method is particularly suitable for single curved
337 components, as the commercially available carbon reinforcements can only adapt to single
338 curvature.
339 Carbon grids also can be used for the reinforcement of already hardened 3D-printed concrete
340 structures as presented by TU Dresden in the context of CONPrint3D technology; see Figure
341 4b [17]. The carbon mesh was incorporated using a laminating technique known from
342 application of carbon reinforced concrete for strengthening or repair; as an example see [23].

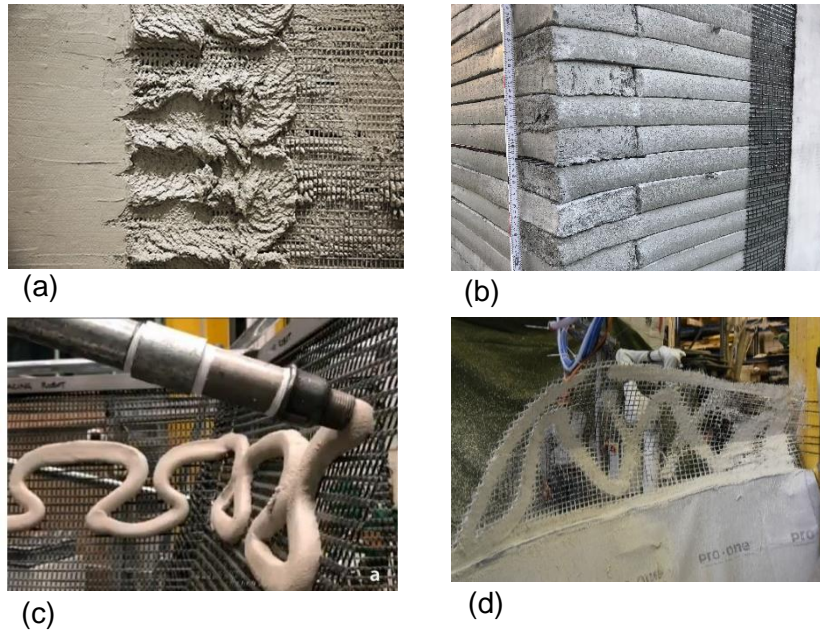


Figure 4. Carbon grids: a) placement of the mesh onto a freshly printed concrete element with subsequent application of a cover layer [22]; b) carbon grid laminated on a 3D-printed wall after concrete hardening [17]; c) extrusion-based printing on a pre-positioned carbon fibre mesh [24]; d) shotcreting on a preplaced carbon-fibre mat using glass-fibre reinforced concrete [25].

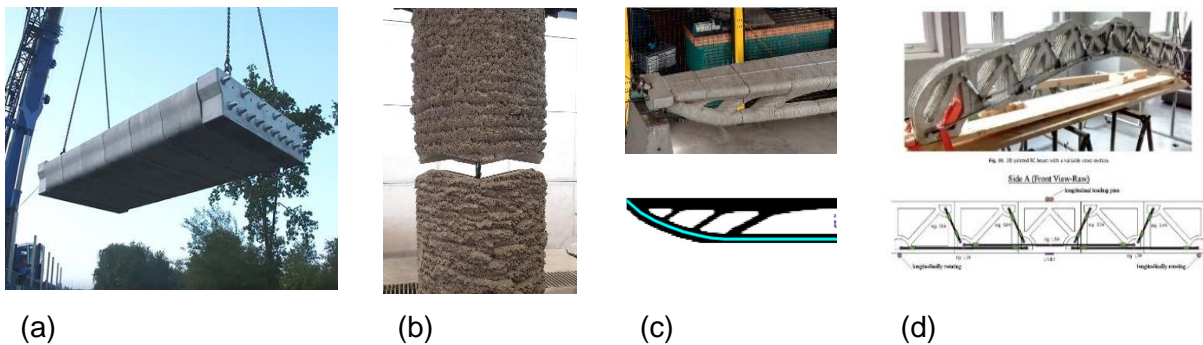
Whereas in the two approaches presented the reinforcement is supported by the previously printed concrete core, the inverse strategy is also subject to investigations. In those cases, the reinforcement mats are pre-placed and concrete is printed onto the pre-defined geometry. In the Sparse Concrete Reinforcement in Meshworks (SCRIM) research project, this is done by extruding concrete from one side onto the previously positioned mesh as depicted in Figure 4c [24]. A similar approach has been followed by the Robotic AeroCrete project of ETH Zürich. However, instead of extruding concrete onto the mesh, the material is sprayed using a shotcreting process; see Figure 4d [25]. In order to avoid the concrete from flying through the mesh, a special spray-gun application is used, adding chopped glass fibres to the concrete right at the nozzle orifice.

2.3.3 Pre-stressing strands (steel, stainless steel, CRP)

An early adopted reinforcement strategy for 3D-printed concrete is the application of pre-stress to eliminate any tensile stresses occurring in the concrete. Generally, the type of ‘post-tensioning without bond’ is utilised. This principle has been applied in a 3D concrete printed bicycle bridge in the Netherlands; see Figure 5a [26]. The designers opted to press six printed elements together perpendicular to their print plane using a common commercially available system with strands anchored in cast concrete end blocks and running through the open inner structure of the printed parts. The design enables counteraction of any prestress loss in the tendons, as the shrinkage characteristics of the printed concrete were not well known beforehand. Large 1:2 scale four point bending tests showed that the element integrity was not lost in several un-/reloading cycles until well beyond the crack moment [27]. Nevertheless, this should remain a point of attention when designing a structural element that relies on unbonded tendons for its structural integrity.

Figure 5b shows a post-tensioned dry joint column manufactured by the Institute of Structural Design at TU Braunschweig in 2019. In this case, column segments were Shotcrete-3D-printed, leaving a central integrated channel. The efficient integration of channels by AM

385 technologies allow the integration of post-tensioning elements after printing. In a subsequent
 386 step the joint surfaces were subtractively machined and then joined and reinforced via post-
 387 tensioning [28].
 388



389
 390 **Figure 5.** Pre-stressing with hardened 3D-printed concrete components: a) conventional
 391 prestressing strands in a printed bicycle bridge [26]; b) post-tensioned dry joint column of
 392 shotcrete-3D-printed segments [28]; c) post-tensioned girder consisting of several segments
 393 produced using 3D concrete printing [29]; and d) external reinforcement system with tightened
 394 bars [30].
 395

396 In the example of this bridge, the geometry of the printed elements was still fairly
 397 straightforward. However, more recent case studies have shown the potential of the use of
 398 this reinforcement strategy in combination with structural optimization methods to obtain more
 399 elaborate and minimalised geometries [27]. The post-tensioned girder with a span of 4 m and
 400 consisting of several segments produced using 3D-concrete printing was developed at Ghent
 401 University; see Figure 5c. By means of topology optimisation techniques, not only was the
 402 concrete distribution optimised, but the optimal shape and curvature of the post-tension cable
 403 were also determined.

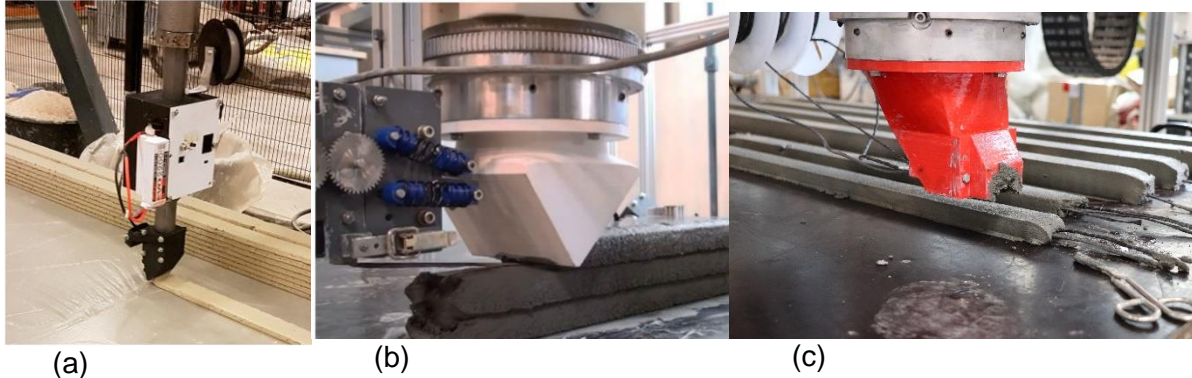
404 Another example for reinforcement systems applied to form a segment structure is external
 405 reinforcement for a 3D-printed truss component developed at the University of Naples
 406 "Federico II" [29]. The patented system uses tightened steel bars. In a first manufacturing step,
 407 only the printing elements of a truss are printed. Then, cavities for reinforcement anchors are
 408 cut out and the reinforcement anchors are inserted and monolithically cast. Eventually,
 409 prefabricated diagonal tension elements are attached to the reinforcement anchors and
 410 tensioned.

411 2.3.4 Cables and yarns

412 In 2017 a method was presented at TU Eindhoven for reinforcement of an extrusion-based
 413 3D-printed concrete, longitudinal filament by directly entraining a high strength steel cable into
 414 the filament [32]. Actively fed from a spool by a small servo motor with an appropriately flexible
 415 cable, this allows a fully automated process that does not reduce the geometrical possibilities
 416 of the 3DCP technology. This technology is clearly only effective in one direction, i.e.,
 417 longitudinal to the filament. Besides several studies that have been published, this concept
 418 has been applied in the bicycle bridge discussed in Section 2.3.3 as secondary reinforcement
 419 to act, in about 10% of the layers of each element, transversely internal to the bridge. Although
 420 initial studies have shown the potential of this technology, several issues remain before it can
 421 be used generally. Besides further development of the equipment to allow fully automated
 422 processing, the minimal reinforcement ratio in an application should be considered because
 423 the maximum tensile force in the applied cables is limited due to their small section size, which
 424 in turn is the consequence of the requirement for sufficient lateral flexibility. Another important

425 issue is the bond between cable and matrix. As the concept relies on the cable acting as
426 conventional reinforcement, this bond has to exceed the cable strength. A recent study [33]
427 showed that the bond quality is highly dependent on the chemical interaction between cable
428 surface and matrix mortar as well as the flow behaviour of the matrix around the cable upon
429 introduction. Inspired by the work at the TU Eindhoven, other research groups have dedicated
430 research efforts on use of thin steel cables in extrusion-based 3D concrete printing; see
431 [34,35].

432



433 **Figure 6.** Introduction of linear reinforcement through or at the printhead nozzle: a) high
434 strength steel cable introduced into extruded filaments [36], b) mineral-impregnated carbon
435 yarns with feeder for placing reinforcement between concrete layers [37]; c) mineral-
436 impregnated carbon yarns introduced into extruded filaments [38].

437 Researchers at the TU Dresden developed an alternative reinforcement material, Mineral-
438 impregnated Carbon-Fibre (MCF) composites, which are particularly suitable for integration
439 into digital fabrication with concrete. In comparison to steel cables or polymer-bound carbon-
440 fibre reinforcement, MCF bonds more effectively with concrete, and in the case of MCF,
441 sufficient bond strength was measured even at temperatures up to 500 °C [39]. The new
442 reinforcement is also less expensive and environmentally friendlier in comparison to the
443 polymer-bound version. However, of major interest is a very high technological flexibility of
444 new reinforcement, since it can be processed and shaped easily in the fresh state and that
445 fully automated [40].

446 Various approaches for introducing MCF into 3D concrete printing were suggested. In the first
447 approach, the MCF reinforcement is placed between subsequently printed concrete layers.
448 The MCF yarn is operated by a feeder attached to the printhead so that reinforcement is
449 deposited in front of the nozzle just before it passes the same spot[37,41]. While the MCF
450 reinforcement is being placed, the previously printed concrete filament acts as a substrate;
451 then the roving is immediately covered by the following printed concrete layer extruded by the
452 printhead; see Figure 6b. The main advantage of this approach is that the MCF can be deposited
453 indeed independently of the concrete. This facilitates the manufacture of elements with
454 complex geometries and the specific reinforcement arrangements; see[37]. The entire process
455 is flexible, especially if a nozzle with a vertical discharge direction is used. On the negative
456 side, a weaker bond between reinforcement and concrete is to be expected in comparison to
457 the solution in which the yarn is integrated into the concrete filament [37,38].

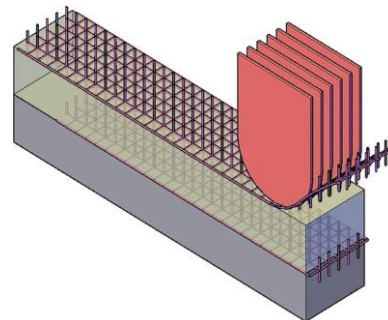
458 Figure 6c shows an alternative approach, called ProfiCarb, which currently enables the
459 integration of up to six MCF yarns simultaneously into the concrete filament through the
460 printhead before concrete deposition. The bond in the joint between the concrete layers is not
461 disturbed by the reinforcement, which is an advantage of this technology [38]. Flexible
462 reinforcement is inserted into a nozzle through an opening on the reverse side of the printhead
463 while the obverse side of the nozzle shapes the concrete filament with the integrated

464 reinforcement. There are also limitations on such a setup: 1) deposition of the reinforcement
465 without concrete is problematic, and 2) placement of the reinforcement is possible only in
466 parallel with the printed layers.

467 Mechtcherine *et al.* [37] pointed out that additional requirements within both approaches can
468 be 1) the free start and stop of MCF supply and integration into concrete and 2) an adjustable
469 degree of reinforcement. Quite clearly these requirements increase the level of sophistication
470 of the printing system and increase its flexibility and overall efficiency in the purposeful use of
471 the reinforcement.

472 2.3.5 Textiles

473 Few studies have investigated the application of textiles made of different materials such as
474 carbon, glass or basalt fibres for reinforcing DFC. Wang *et al.* [42] at the Loughborough
475 University placed plane glass fibre textile on a print concrete layer and covered it then by
476 printing the next concrete layer; see also Figure 7a. Mechtcherine and Nerella [43] proposed
477 an 'in-process' reinforcement method to place a special 2.5D textile between individual
478 concrete layers to counteract the possible formation of 'cold joints' between printed layers; see
479 Figure 7b. The aim of this method is to stitch each of the two adjacent layers together by the
480 protrusion of individual fibres in the vertical direction. Obviously, a specific print head needs
481 to be designed for accurate automatic placement of the textile. Apart from prevention of cold
482 joints, concrete layers are reinforced in the printing direction as well.



(a)

(b)

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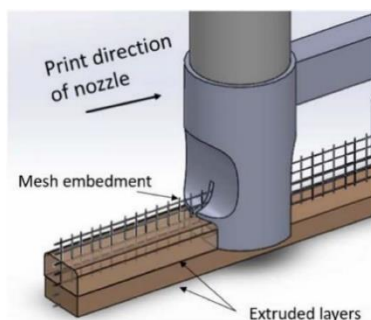
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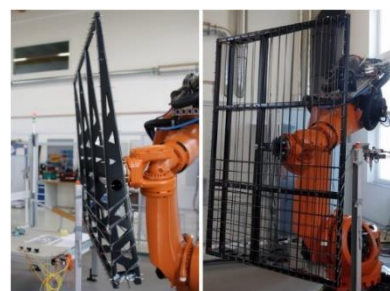
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493

494



(c)



(d)

495 **Figure 7.** Reinforcement strategies using textiles: a) print concrete specimen reinforced with
496 a planar, glass fibre textile [42]; b) placement of special 2.5D textile between two adjacent
497 layers in the printing plane [43]; c) in-process placement of galvanised steel wire mesh in the
498 interlayer direction (across the layers) [44]; d) automated manufacturing of 3D reinforcement
499 structure for a balcony using a robot-based wrapping process for mineral-impregnated carbon
500 fibre composites [40].

501

502 Recently, Marchment and Sanjayan [44] proposed an 'in-process' reinforcement method
503 called Mesh Reinforcement, in which a galvanised steel wire mesh was placed in the middle
504 of each printed layer while the concrete layers were being printed to provide reinforcement in
505 the interlayer direction, i.e., across the layers; see Figure 7c. The embedded mesh in each

506 layer was overlapped in the vertical direction of the interface transverse to the layer to ensure
507 continuity of reinforcement. A special nozzle was designed to allow the insertion of the
508 continuous reinforcing mesh in the middle of the layers' being printed. The reinforcing mesh
509 should have appropriate rigidity, diameter, and aperture of the grids to provide adequate bond
510 and anchorage within the printed layer, accommodate the mobility of the nozzle during
511 deposition, and allow placement and feeding through the nozzle system. While the proposed
512 method proved effective in providing a continuous 'in-process' reinforcement for lab-scale 3D-
513 printed straight walls, the process still needs to be automated, and further testing should be
514 done on larger scale components and curved structures. In addition, the method may be
515 optimised by autonomous stitching together of mesh via rebar ties to reduce/eliminate the
516 overlap length and chance of collision during the process.

517 Mechtcherine *et al.* [40] used Mineral-impregnated Carbon Fibre composites (MCF) for
518 automated manufacturing of 1D- (bars and strips), 2D- (mats), and 3D- (e.g., shells)
519 reinforcement elements. Figure 7d shows a robot-based wrapping process for manufacturing
520 a 3D reinforcement for a balcony, where a supporting frame was mounted at one single point
521 to the robot, and the wrapping process was conducted by moving the supporting frame around
522 the impregnated yarn, guided by a fixed shaping nozzle.

523

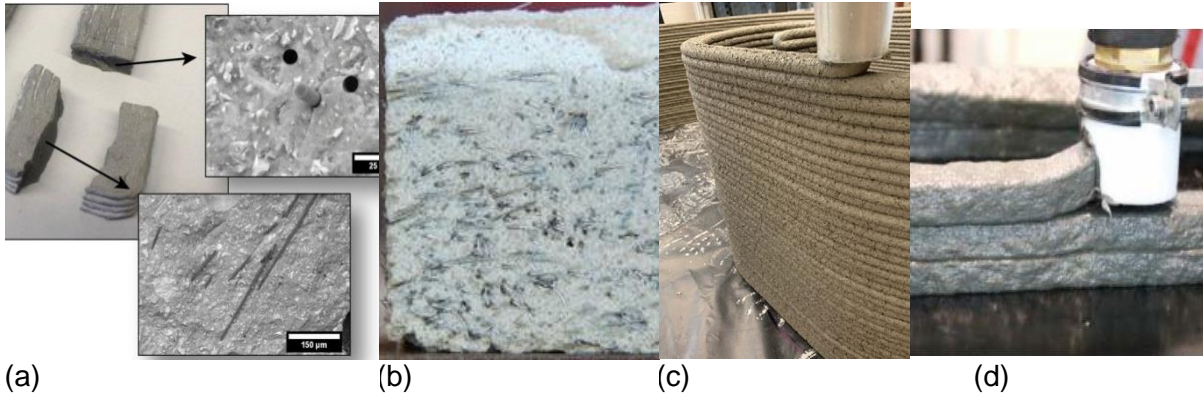
524 **2.3.6 Dispersed short fibres**

525 Several studies investigated the application of various short fibres made of polymer, carbon,
526 glass, steel or stainless steel as disperse reinforcement for DFC [1]. They can be premixed
527 into the dry mortar, added during concrete mixing, or introduced into the mortar/concrete just
528 prior to deposition. The former two cases have the distinct advantage that no custom
529 equipment is needed, allowing easy integration into the printing process. The latter, on the
530 other hand, may be required due to pump-fibre incompatibility and would need specific
531 equipment [45]. However, this still means that the printing itself is unencumbered by additional
532 process steps.

533 During printing fibres do not take a random orientation, but mostly one that globally
534 corresponds to the direction of the printing path. The actual fibres' orientations are the result
535 of a complex interaction between matrix material properties, e.g., viscosity, fibre properties,
536 e.g., aspect ratio and transverse stiffness, and the print facility, e.g., pumping pressure and
537 nozzle geometry). Generally, fibres will only provide reinforcement in the print plane because
538 they do not cross filament interfaces. However, a study showed this might be overcome by
539 providing a tongue-and-groove type of surface accentuation of the filament; see [46].

540 Hambach and Volkmer [47] reported on the mechanical properties of cement paste reinforced
541 by different types of 3- to 6-mm-long fibres, including carbon, glass, and basalt fibres. The
542 inclusion of the fibres resulted in high flexural strength of the printed specimens, up to 30 MPa.
543 ESEM micrographs of fractured specimens confirmed a pronounced alignment of fibres in the
544 printing direction; see Figure 8a.

545



546 **Figure 8.** Examples of the use of dispersed short fibres: a) a sample containing aligned
 547 reinforcement fibres and corresponding ESEM micrographs showing fibre orientation
 548 (perpendicular and parallel to the fracture surface of the specimen) [47]; b) printed specimen
 549 reinforced by short steel fibres and sawn parallel to the printing direction [48]; c) 3D-printing
 550 process with UHPFRC reinforced by short steel fibres [49]; d) 3D-printing process with SHCC
 551 containing PE fibres [50].
 552

553 Bos *et al.* [48] investigated the effect of the inclusion of short, straight steel fibres on the
 554 performance of 3D-printed specimens, and the results were compared with the counterpart
 555 cast specimens. A strong alignment of fibres in the printing direction was observed; see Figure
 556 8b. Still the results showed that the fibre-reinforced specimens exhibited significantly higher
 557 flexural strength as compared to the specimens made of plain mortar. However, all specimens
 558 exhibited deflection-softening behaviour after reaching peak load.

559 Arunothayan *et al.* [49] recently reported the systematic development of a non-proprietary, 3D-
 560 printable ultra-high performance fibre-reinforced concrete (UHPFRC) reinforced with 2% by
 561 volume of 13 mm long steel fibres; see Figure 8c. The printed UHPFRC exhibited high flexural
 562 strengths (up to 39.5 MPa) along with deflection-hardening behaviour. The modulus of rupture
 563 of the printed UHPFRC specimens was significantly higher than that of the mould-cast
 564 specimens, due to the alignment of short fibres in the printing direction during the extrusion
 565 process.

566 Ahmed *et al.* [45] presented a device to introduce generic particles, which could be different
 567 types of fibres, into the mortar in an extrusion-based 3D concrete printing facility just before
 568 printing, thus circumventing potential compatibility issues of, for example, aggregates with the
 569 main pump of the system. Amongst others, 24-mm-long glass fibres were introduced, which
 570 resulted in semi-plastic failure behaviour and high deformation capacity.

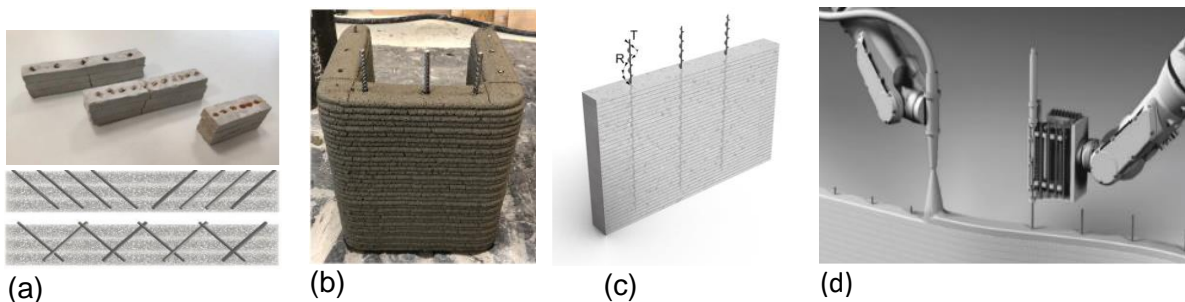
571 To date few studies have reported the development of 3D-printable, strain-hardening
 572 cementitious composites (SHCC) reinforced by short polymeric fibres such as polyvinyl
 573 alcohol (PVA) and high-density polyethylene (HDPE) fibres. Li *et al.* [46] recently provided a
 574 state-of-the-art review on 3D printing with SHCC. 3D-printed SHCC exhibits tensile ductility
 575 comparable to that of cast SHCC. Ogura *et al.* [50] reported that printed HDPE-SHCC
 576 specimens exhibited pronounced strain-hardening behaviour in uniaxial tension for fibre
 577 concentrations as low as 1%; cf. Figure 8d. Chaves Figueiredo *et al.* [46] presented a
 578 quantitative methodology based on rheological parameters for development of printable
 579 SHCC reinforced by PVA fibres. In another study, Zhou *et al.* [51] reported the development
 580 of printable SHCC reinforced by different percentages of PE fibres, exhibiting very high tensile
 581 strength and tensile strain capacity of up to 5.7 MPa and 11.4%, respectively. The results of
 582 several of the abovementioned investigations showed that the printed specimens exhibited
 583 superior tensile performances to cast specimens, which was attributable to the strong fibre
 584 alignment caused by the extrusion process. However, for a mixture with PVA fibres, Chaves
 585 Figueiredo *et al.* [52] reported that the fibre orientation was not simply parallel to the

586 longitudinal direction, but rather seemed to be influenced by differential flow between the in-
587 and outside of the filament, too. In order to address the lack of effectiveness across the
588 interfaces, it was shown by Li *et al.* [46] that a tongue-and-groove type of surface accentuation
589 to the printed filament can significantly improve the post-crack strength of a notched beam in
590 three-point bending, thereby suggesting the issue of lack of out-of-plane ductility might be
591 solved.

592

593 2.3.7 Penetration reinforcement

594 A few studies have introduced an ‘in-process’ reinforcement method in which nails, screws
595 and conventional steel bars are driven through a predefined number of freshly printed layers
596 of concrete. The aim of these methods is to provide reinforcement across the concrete layers.
597 Although in the available studies, as presented in the following, the reinforcements manually
598 penetrated the concrete layers, in practice the placement of reinforcement can and should be
599 automated. Penetration of the reinforcement causes different levels of disturbance to the
600 printed layers, depending on the penetration depth among other parameters, specifically, if
601 conventional steel bars are used. Obviously, the bond between reinforcement and printed
602 concrete should be adequate to ensure the composite action. Therefore, the number of layers
603 into which the reinforcement can be driven while yielding sufficient bond strength is limited.



604 **Figure 9.** Reinforcement approaches using penetration: a) penetration by steel nails with
605 different spacing and orientation through freshly printed concrete [53]; b) penetration of 350
606 mm long steel bars through printed concrete [54]; c) inserting screws by a combination of
607 translational and rotational movement into freshly printed concrete [55]; d) vision for
608 penetration of short reinforcement bars into Shotcrete-3D-Printing process using an
609 automated, robot-guided process [56].

610 Perrot *et al.* [53] used nails of 30 mm length and 1.8 mm diameter with different spacing of 10,
611 15, 20 and 30 mm and various orientations, i.e., vertical, inclined and crossed, to the printed
612 concrete layers. Specimens consisted of three or ten layers; see Figure 9a. For the 3-layer
613 specimens tested perpendicular to the layer’s direction, the vertical nails did not contribute to
614 the bending capacity, while the inclined and crossed nails increased the bending capacity by
615 up to 50% as compared to the unreinforced specimens. For the 10-layer specimens tested
616 parallel to the layer’s direction, the nails, irrespective of their orientation (vertical or inclined),
617 increased the bending capacity by up to 50%. The comparison between the smooth and rusty
618 nails showed a negligible effect of the nails’ surface roughness on bending capacity but had a
619 significant effect on post-peak behaviour. For the smooth nails, the load post peak dropped to
620 zero due to slippage, while for the rusty nails the load did not drop to zero, but to a constant
621 residual value.

622 Recently, Marchment and Sanjayan [54] introduced a method in which a deformed steel bar
623 of 7 mm diameter was penetrated manually through a number of freshly printed layers; see
624 Figure 9b. Pullout tests were conducted to characterise the bond between the bar and the
625 printed concrete along the penetration depth. It was found that the bond was higher at the

626 bottom of the penetrated depth and gradually decreased towards the top. The bond between
 627 the bar and printed concrete specimen near the bottom of the penetrated depth was similar to
 628 that of the cast specimen. A strong correlation was found between the penetration length and
 629 reduction in bond strength.

630 Hass & Bos [55] presented a new reinforcement method in which screws are inserted into
 631 freshly printed concrete. The combination of translational and rotational movement provided
 632 very good bonding and few defects between the screw and the freshly printed concrete, which
 633 is a major downside characteristic of merely translationally pressing any sort of element into
 634 the relatively rigid mortar. This was confirmed by the results of pull-out and three-point bending
 635 tests, in which premature pull-out failure of the screw was not recorded, but rather failure was
 636 observed in the printed concrete itself. Although manually applied in this study, the technology
 637 could be automated and can be effective in any direction except longitudinally to the print
 638 filament. It requires an additional, intermittent sub-process during printing, of which it may
 639 therefore influence efficiency negatively. There will be a time window in which the technology
 640 can be applied and related to the setting rapidity of the print mortar in use.

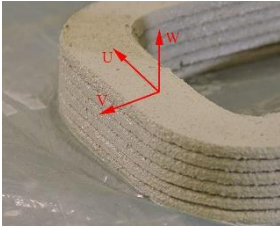
641 Freund *et al.* [56] investigated three different methods for placement of a short bar, of diameter
 642 12 mm and made of steel or carbon, into the Shotcrete-3D-Printing process; see Figure 9d.
 643 These methods include a) direct insertion, b) insertion into a grouting mortar, and (c) screwing
 644 the bar into the printed concrete. Pull-out test results and evaluation of computer tomography
 645 images confirmed that method (a) resulted in a reduced bond as compared to the other two
 646 methods due to a process-related cavity formed between the bar and the surrounding
 647 concrete. On the other hand, methods (b) and (c) resulted in a significant enhancement of the
 648 bond between the bar and concrete.

649

650 **2.4 Summary of the reviewed reinforcement approaches according to their**
 651 **advantages and limitations**

652 Based on the above review, which is organised according to reinforcement types and
 653 materials, reinforcement approaches and their key features can be identified. These
 654 approaches are listed in Table 1 and some of their perceived advantages and limitations are
 655 described. The concepts with similar advantages and limitations are listed together, based on
 656 the process and the type of reinforcement that have been developed and demonstrated so
 657 far. The directions in which the reinforcement can be provided are defined with regards to the
 658 fabrication rather than the product. The fabrication direction *u* is defined as the direction of the
 659 layer along the layer or print direction; *v* is the interlayer or layer stacking direction; and *w* is
 660 the out-of-plane direction. See also the small sketch internal to the table. The product being
 661 fabricated may have a different coordinate system such as *x*, *y* and *z*, e.g., *x* and *y* being
 662 horizontal and *z* being vertical).

663 **Table 1.** Approach listed according to their advantages and limitations

Reinforcement approach	Advantages	Limitations
Post-installed reinforcement <ul style="list-style-type: none"> • reinforcement bars placed and grouted [57–64] • prestressed reinforcements [26] • external reinforcement [65] 	Structural requirements such as robustness, ductility and tensile strength, shrinkage, creep, and crack width limitations can be satisfied with these reinforcements. These types of reinforcements have been used in reinforced concrete for many decades and are technologically mature with regard to design and implementation.	Require post-processing. Coordinates used in this table: 

Pre-installed reinforcement <ul style="list-style-type: none"> • Print around the reinforcement [66,67] • Mesh Mould [68,69] • Print over reinforcements [11,70] 	These approaches can satisfy most of the structural requirements mentioned above. Pre-installing reinforcements before casting concrete is a traditional method. However, printing concrete is a relatively new concept.	Require pre-processing.
Cable entrainment in the filament [32,34–36,71,72] Continuous fibre entrainment [35,71]	In-process reinforcement method.	Only in u-direction. Bars cannot be used.
Overlapping mesh reinforcement [44]	In-process reinforcement method; u- and w-directions can be reinforced.	Not in v-direction; bars cannot be used.
Penetrating reinforcement [53–56,74–76]	In-process reinforcement method; cross-layer (w-) direction can be reinforced.	u and v directions have not been attempted; in-process, but two separate parallel processes are required.
Dispersed short fibres [45,46,81–84,48,49,51,52,77–80]	Easy to implement without additional equipment; in-process method; effective for preventing plastic shrinkage cracks, reducing crack widths, and increase in toughness.	Mainly for non-structural purposes, structural member ductility and structural robustness cannot be achieved due to discontinuities of the fibres.
Welded bars [10,14,15,20,85,86]	In-process method; u-, v- and w-directions are possible.	Quality and steel property control need to be monitored carefully; process speed and cost considerations may outweigh the technical benefits.
Printed polymeric reinforcement [87–89]	Complex shaped reinforcements in all u-, v- and w-directions are possible; it can be used for special arrangements of structural reinforcements.	Non-structural reinforcement only; limited tensile strengths.

664

665

3. Previous reviews and classifications

666 The great variety of approaches for integration of reinforcement in digital fabrication with
667 cement material calls for a classification. The available framework to build such a classification
668 on is fairly limited. Conventional structural concrete engineering guidelines hardly provide a
669 handhold. In the vast majority of concrete structures, reinforcement is provided by linear
670 elements, generally made of steel: normal strength steel for passive reinforcement, and high-
671 strength steel for active reinforcement, i.e., prestressed. The use of other materials for such
672 bars, e.g. glass fibre reinforced polymer (GFRP) and carbon fibre reinforced polymer (CFRP),
673 is possible but remains limited to special cases, since these types of reinforcement are not
674 covered by major codes such as the Eurocode 2 [90]. In a limited number of applications, the
675 use of short fibres as reinforcement is allowed to obtain the required functional tensile strength
676 and hence a reduction in conventional reinforcement. In a few situations, such as industrial
677 floors, short fibre reinforcement can even be used without reinforcement bars. Occasionally,
678 alternative reinforcements such as textile fabrics are applied, but altogether the options in
679 conventional concrete are limited to such an extent that an explicit classification has not
680 emerged.

681 Within the field of DFC itself, the attempts at classification have also been scarce. This is
682 mainly due to the sheer novelty of the reinforcement technologies; most of them have been
683 developed only in the last five years. Several review papers discuss the state of affairs with
684 regard to the development of reinforcement for DFC, but they usually do not provide more
685 than a list of more or less logically ordered methods. Wangler *et al.* [1], in Section 3.2, provide
686 an extensive state-of-the-art review of reinforcement strategies but do not present a specific
687 organising scheme. Similarly, several reinforcement solutions are discussed by Mechtcherine
688 and Nerella [43]. Menna *et al.* [91] extensively discuss structural engineering of DFC
689 structures, thereby inevitably touching on the issue of reinforcement. Amongst others, they

690 discuss a number of realised DFC projects in depth, including the issue of reinforcement and
691 how that has been addressed in each project. While the article provides an interesting angle
692 from the perspective of actual use of reinforcement, it does not offer a comprehensive basis
693 for classification, especially not with respect to the manufacturing processes in the context of
694 DFC.

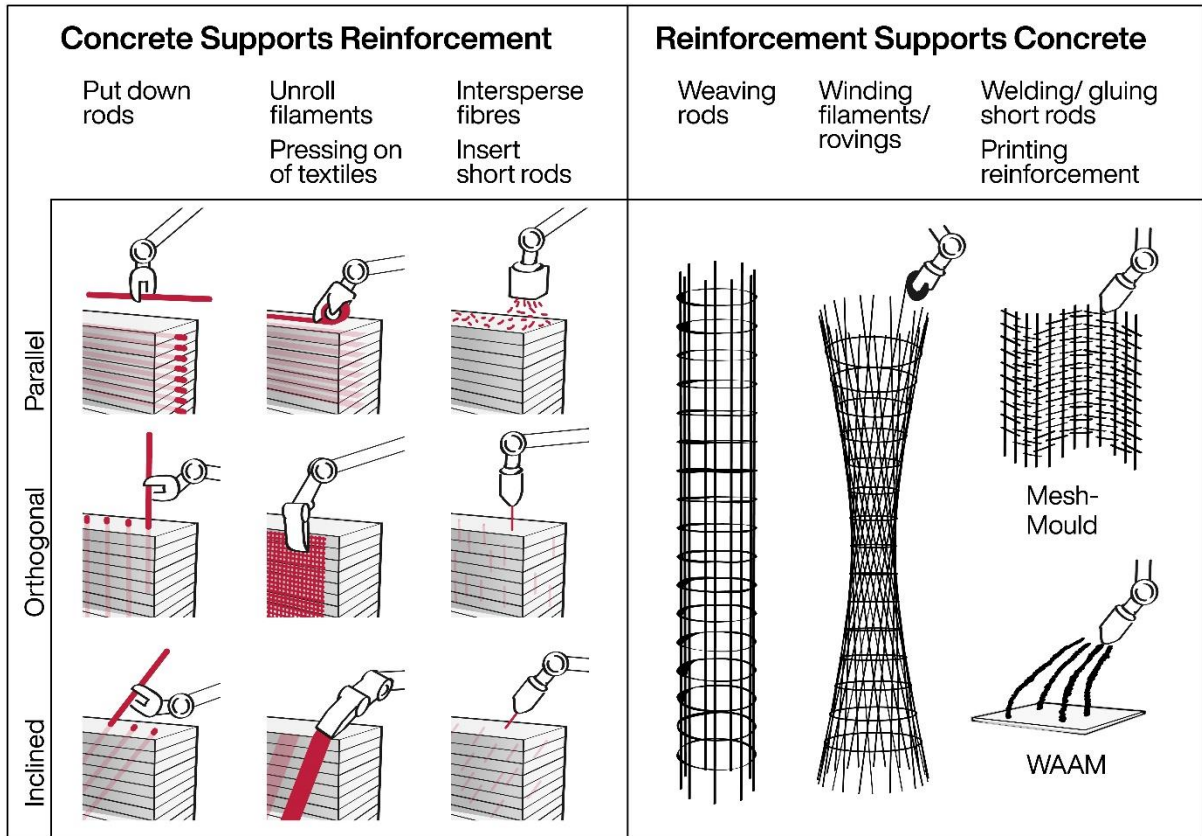
695
696 To date the most complete discussion can be found in Asprone *et al.* [92]. The authors present
697 a two-parameter classification based on the moment of application of the reinforcement
698 respective to the manufacturing process on the one hand, and the structural principle on the
699 other. In the manufacturing stage, they recognise the substages before, during, and after the
700 concrete deposition. 'Before' and 'after' should be understood as being at a moment in time
701 independent of the moment of deposition of the concrete; i.e., the time between the shaping
702 process of concrete and the placement of reinforcement exerts significant influence neither on
703 the performance nor on the manufacturing process.

704
705 As structural principles, 'ductile material', 'DFC composite', 'compression loaded structures',
706 and 'hybrids' are identified. The former generally translates into the application of short fibres,
707 as the intent is to provide a ductile material that for the purpose of structural calculation can
708 be treated as homogenous, albeit possibly anisotropic. The DFC composite is a combination
709 of distinguishable components to which distinct compressive and tensile properties can be
710 assigned for structural calculations of the constituted sections. Compression-loaded structures
711 such as arches or domes avoid the need for reinforcement by eliminating tensile stresses,
712 while hybrids could be a combination of any of the three previously described structural
713 principles.

714
715 Using the moment of application and the structural principle as two parameters, Asprone *et*
716 *al.* [92] classify a number of studied cases. Although this classification enables a clear
717 positioning of individual solutions, it does not cover more detailed aspects regarding
718 manufacturing processes or directional dependency.

719
720 Kloft *et al.* [18] also attempted an organization of reinforcement strategies for DFC; see Figure
721 11. Like Asprone *et al.* [92], they organise the various methods into a matrix, but one that is
722 based on quite different parameters. The columns represent the primary organisational
723 principle. Distinction is made between cases in which concrete supports reinforcement,
724 meaning that concrete is placed first, and those in which reinforcement supports concrete, i.e.,
725 the reinforcement is positioned first and acts as a (semi-open) formwork or scaffolding for
726 concrete. The further distinction within each of these two groups is made according to specific
727 processes: putdown rods, unrolled filaments/pressed-on textiles, interspersed fibres/inserted
728 short rods are identified in the concrete-supports-reinforcement group, while weaving rods,
729 winding filaments / rovings, and welding/gluing short rods/printing reinforcement are the sub-
730 categories of the other group.

731 The horizontal orientation of the matrix is reserved for an indication of the effective direction
732 of the proposed reinforcement solution: parallel, orthogonal, and inclined. So seen, this
733 classification addressed directional dependency although it ignores the orthogonal direction
734 in the horizontal plane. Furthermore, some categories are hard to distinguish; particularly, the
735 'put down rods' and the 'insert short rods' are very similar. An advantage might be that this
736 classification effort is less abstract than the one proposed by Asprone *et al.* [92] and that it
737 includes directionality of reinforcement's effectiveness.

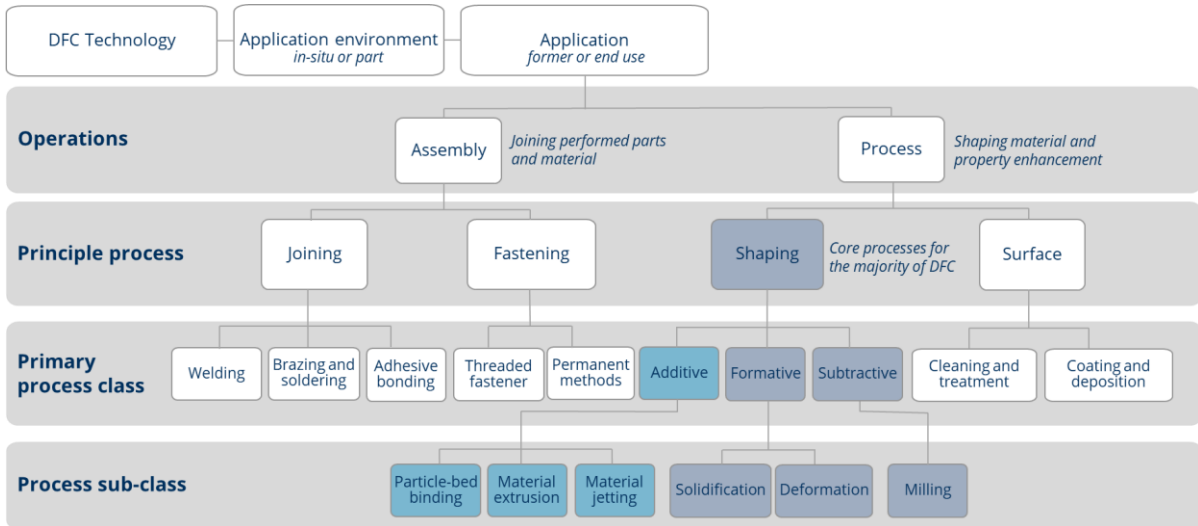


738 **Figure 11.** Organizational scheme of DFC reinforcement strategies, adapted from Kloft *et al.*
739 [18].
740
741

742 Taken in sum, these early attempts purport to show that there is a need within the field to
743 develop a solid basis to discern and position individual solutions within the wide variety of
744 options being developed. In doing so, however, it is not straightforward as many variables,
745 timing, application method, structural principle, directionality, and so forth, can be used as
746 organizing principles, but it is not yet clear which ones are the most suitable.
747

748 **4 The classification framework and process description**

749 The review of existing approaches on integration of reinforcement into digital fabrication with
750 concrete as presented in Section 2 as well as previous reviews and classification efforts as
751 outlined in Section 3 show a great range of relevant parameters and features to be considered
752 when designing both reinforced structures/elements and fabrication processes. The authors
753 of this article believe that it is neither possible nor necessary to accommodate all the
754 parameters in one classification. The classification framework suggested here focuses on the
755 processes for integration of reinforcement into DFC, and it is designed as an extension of the
756 RILEM process classification framework for DFC technologies [7]. The RILEM framework is
757 an over-arching scheme that helps to define, describe, and classify DFC processes using well-
758 defined intersection terms in interdisciplinary field where construction meets manufacturing
759 and automation; see Figure 12.

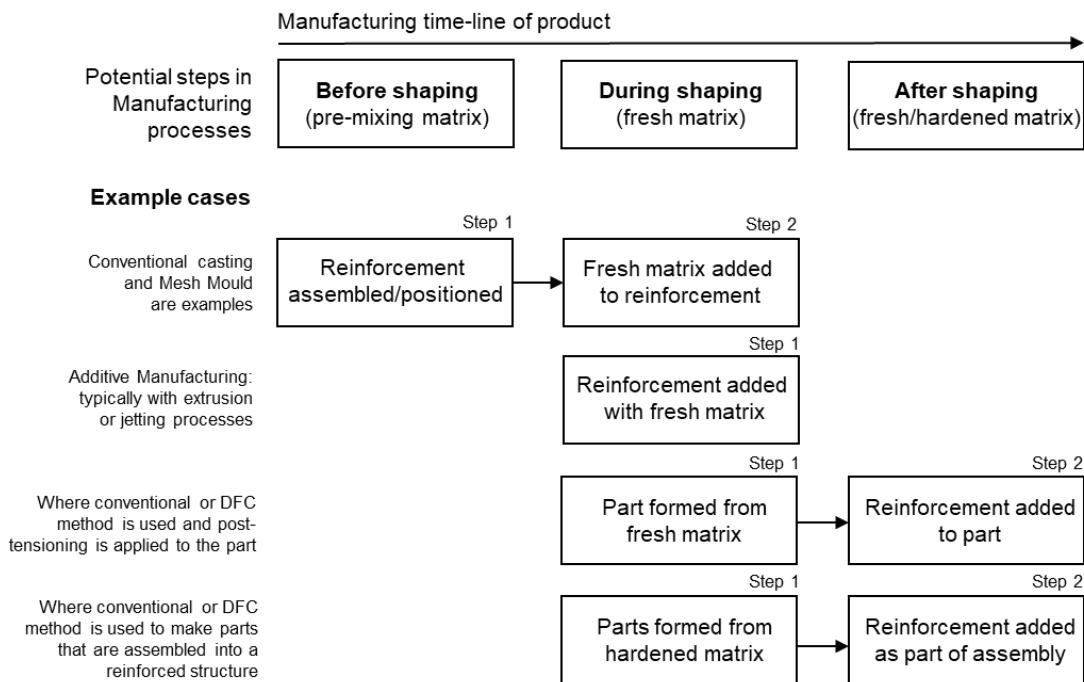


760

761 **Figure 12.** RILEM Process Classification Framework for DFC, adapted from Buswell *et al.* [7].

762

763 It is important to note that the RILEM framework in many instances provides description of a
 764 single process step. While DFC uses many different manufacturing operations methods and
 765 approaches to shape the material into the form it maintains in its hardened state, often more
 766 than one process step is required to manufacture an end-use product such as a structural
 767 element. It holds especially true with respect to the integration of reinforcement. Identifying
 768 these steps helps to define boundaries and so helps in clearly defining the principal operations
 769 involved in a process. Figure 13 depicts four cases that relate to the introduction of reinforcement
 770 to the mortar/concrete: 1) where the reinforcement is created in one step, and
 771 then the concrete is shaped in another; 2) where the concrete and reinforcement are added
 772 as part of a combined process, typically Additive Manufacturing; 3) when post tensioning is
 773 used on a hardened part; and 4) when post-tensioning is used to assemble multiple parts into
 774 a structure.



775

776 **Figure 13.** Combining mortar/concrete shaping and the placement of reinforcement.

777 The classification suggested here considers the sequence of distinct processes according to
778 the manufacturing timeline of product as a starting point; see Figure 14. While building upon
779 the RILEM framework, the classification also provides a link to structural design issues by
780 naming corresponding options for the choice of reinforcement according to the following
781 primary categories: cage, mesh/textile, bar, cable/yarn, and short fibre. Indeed, the proposed
782 classification begins right there where the RILEM framework ends, i.e., at the level of the DFC
783 process subclass for shaping concrete either additively, i.e., particle bed binding, material
784 extrusion, material jetting, or formatively, i.e., solidification, deformation; cf. Figure 12.

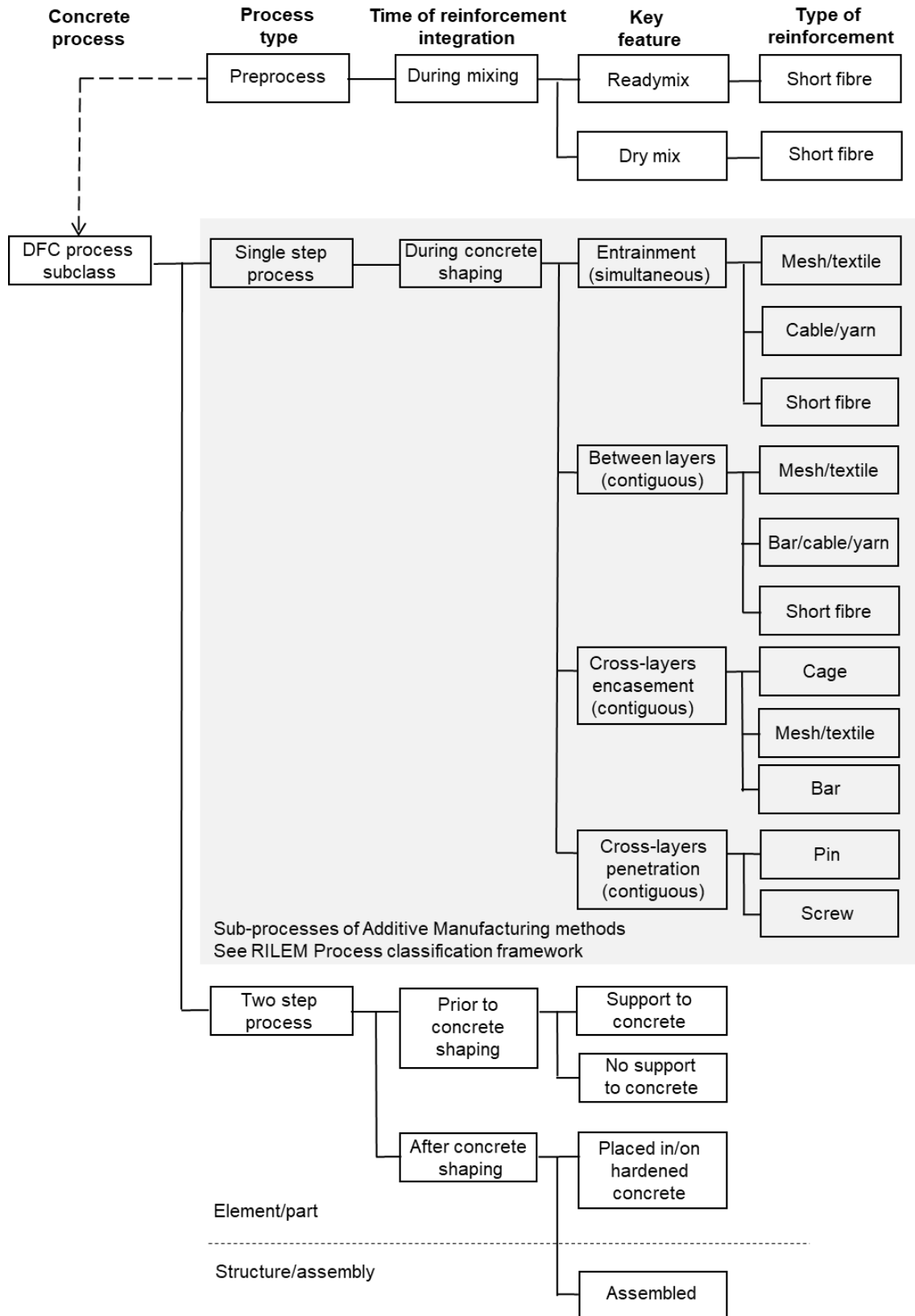
785 For Additive Manufacturing methods with concrete, reinforcement can be integrated within a
786 single process step as a sub-process occurring during concrete shaping. This is not feasible
787 for formative processes. However, the integration of reinforcement prior to or after concrete
788 shaping, i.e., in a separate step, can be performed both with additive and formative concrete
789 processes in a similar manner. These options are indicated in the classification as two-step
790 processes. Additionally, concrete mixing is defined as a pre-process preceding any concrete
791 shaping process. During mixing short fibre may be added as dispersed reinforcement to
792 produce either ready mix or dry mix for further use in both single-step and two-step DFC
793 processes. A prominent example for AM processes is material extrusion with SHCC; for
794 example, see Figure 8d. Here and further in this section references to the figures presented
795 in Section 2 will be made for the sake of clarity.

796 There are four categories for integration of reinforcement during the concrete shaping process;
797 see Figure 14. The first is entrainment into concrete bulk before material deposition. For
798 extrusion-based processes entrainment of cables, in Figure 6a, and yarns, in Figure 6c, can
799 be realised as a part of printhead process. Short fibre and textile/fine mesh can be entrained
800 as well. Note that the dispersion of short fibre requires energy for intermixing with the concrete
801 matrix, which can be done both in the material extrusion process, mixing of fibre as a part of
802 the printhead process, and in the material jetting process, in- or outside the nozzle.

803 The second category is the placement of reinforcement between layers of concrete. In contrast
804 to the entrainment where the deposition of concrete and the entrained reinforcement occur
805 simultaneously, the process is contiguous in this case. Examples are given in Figure 7b for
806 textile, in Figure 2a for bars, in Figure 8b for yarns, all positioned horizontally in the longitudinal
807 direction of concrete filaments arranged vertically one over another. However, other
808 arrangements are technically possible as well, e.g., deposition of a yarn or stripe of textile on
809 the vertical face of a concrete filament and depositing the next filament laterally onto the yarn
810 or textile and previously deposited concrete filament. This applies also for short fibre, which
811 can be sprinkled on both horizontal and vertical concrete surfaces. The deposition of
812 reinforcement between horizontal layers can be used in all three subclasses of AM incl.
813 particle-bed binding.

814 Cross-layer encasement is also a contiguous process. Vertical or inclined fragments of
815 reinforcement as well as the attendant horizontal components are placed before the next
816 concrete layer is deposited. The concrete layer encases the fragments but still does not cover
817 their tops, since further reinforcement fragments will be attached there and / or in order to
818 establish cross-layer reinforcement. Vertical or inclined stripes of mesh/textile can be used in
819 this category as in Figure 7c as well as vertical or inclined bars or little cage fragments locally
820 assembled as in Figure 3d or additively produced as in Figure 3d. The fourth category also
821 addresses cross-layer arrangement of reinforcement; however, the key feature here is that
822 the reinforcement is induced by penetration while the concrete is still in the fresh/plastic state.
823 Typically, straight, one-dimensional pieces of reinforcement are used for the purpose, either

824 pins (see Figure 9a) or screws (see Figure 9c). They can be placed perpendicular to the layers'
 825 plane or inclined to it.



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Figure 14. The process classification framework for integration of reinforcement into DFC technologies (PC4IR-DRC)

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The two-step processes are subdivided into two categories according to the time of the reinforcement integration, i.e., prior to or after concrete shaping. The key feature of reinforcement placed prior to concrete shaping is its support for the concrete or the absence of such support. If reinforcement provides support to concrete, the concrete shaping process is a formative one since the shape of the element is defined by the supporting reinforcement, which acts as a mould or sheathing; cf. Figure 4c, -d. In the no-support-case, both formative and additive concrete shaping approaches are applicable. Finally, in the category 'after concrete shaping' we distinguish between 1) placement of reinforcement in or on hardened concrete as a process step to complete a structural or non-structural element; see, for example, Figure 3a or 4b and 2. Assembling elements/parts to a structure are illustrated in Figure 5a. In the latter case, post-tensioned cables have been used efficiently.

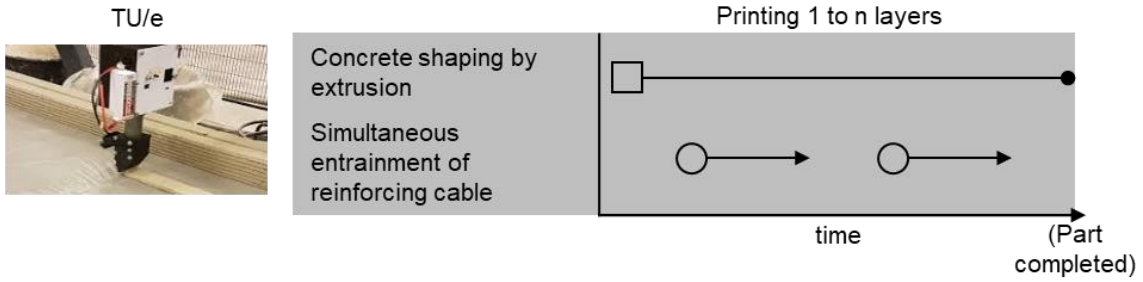
Note that the suggested classification for the integration of reinforcement does not cover the step of assembling or shaping of reinforcement either in a conventional or digital manner. Indeed, it would be a separate process step to be considered and described. However, this can be done by using RILEM Classification Framework for DFC as basis. For example, the manufacturing process of Mesh Mould reinforcement can be described by operation assembly, with joining as the principal process step and welding as the primary process class. Certainly, not in every case is the process allocation is so straight forward since the scheme is very generic on purpose and does not exclude its extension in the future. For example, the WAAM process for manufacturing of steel reinforcement can be classified as an additive shaping process, a kind of extrusion as a process sub-class in which the printing nozzle deposits moulded material on given coordinates upon which steel phase change occurs due to cooling.

Finally, some examples of applying the new classification to describe digital fabrication processes with reinforced concrete should be provided in form of simple process flow charts; see Figure 15. The first example is a single-step process in which reinforcing cable is entrained into the concrete filament and thus deposited simultaneously with concrete shaped by extrusion. The purely digital process continues until the printed part/element is finished, while the sub-process of the cable entrainment able can be interrupted on demand by cutting the cable and stopping its feed; and the entrainment can be eventually resumed by restarting the feed. In such a way the segments of the bicycle bridge in Gemert were produced. Note that for this single-step process the segment is the end product.

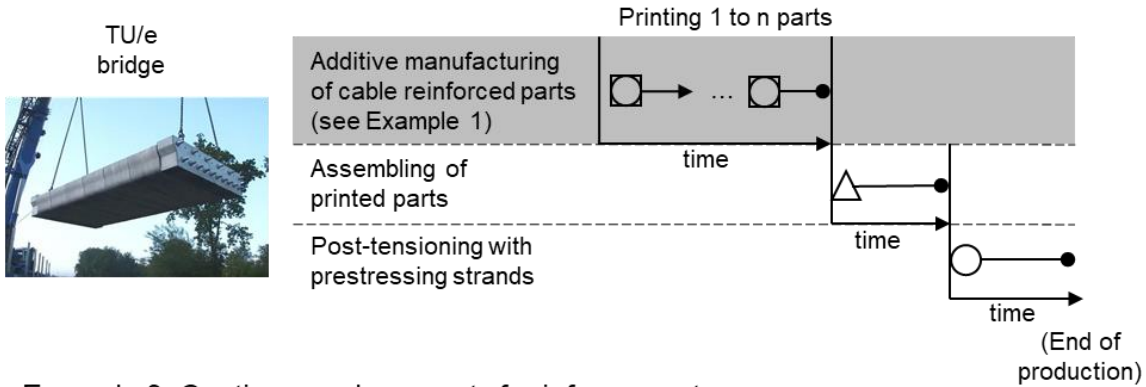
Example 2 shows the entire multi-step process of the bridge fabrication. The first process step is equivalent to Example 1 with the difference that not a single part / segment is produced, but a number n of segments are printed consequently. The second process is assembling of the parts / segments. The final, third process is placing of prestressing strands and post-tensioning them. Note that the second and third processes a) were performed in a conventional manner in the given example but can in principle be digitised and automated, and b) do not depend on the process of segment production, i.e., if it is additive or formative. The final product of the process chain is the bridge itself.

Example 3 illustrates the single-step process which concrete is shaped additively by extrusion and cross-layers reinforcement is introduced contiguously. First several layers of concrete are deposited one upon the other followed by nailing layers of fresh concrete with steel pins. After distinct number of pins is inserted, the concrete printing is resumed to deposit further several layers before this procedure is interrupted again to give way to penetrating pins. Such alteration can be repeated numerous times until the printed product is completed. In the given example it is a wall-like demonstrator.

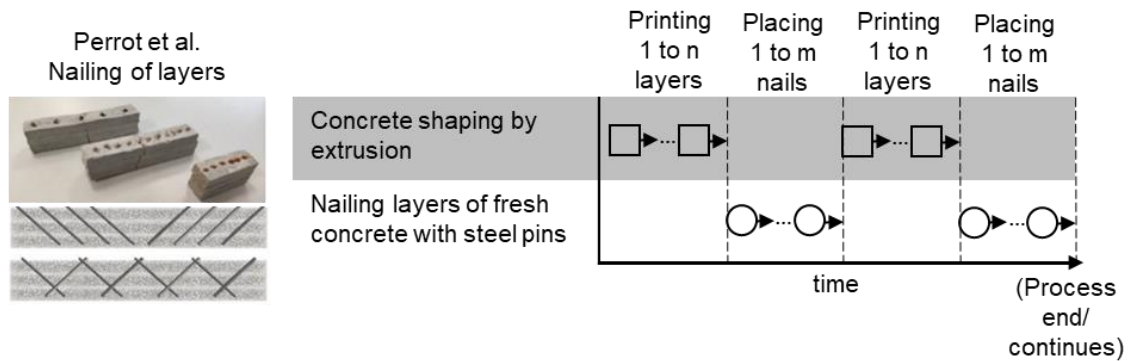
Example 1: Placement of reinforcement during concrete shaping



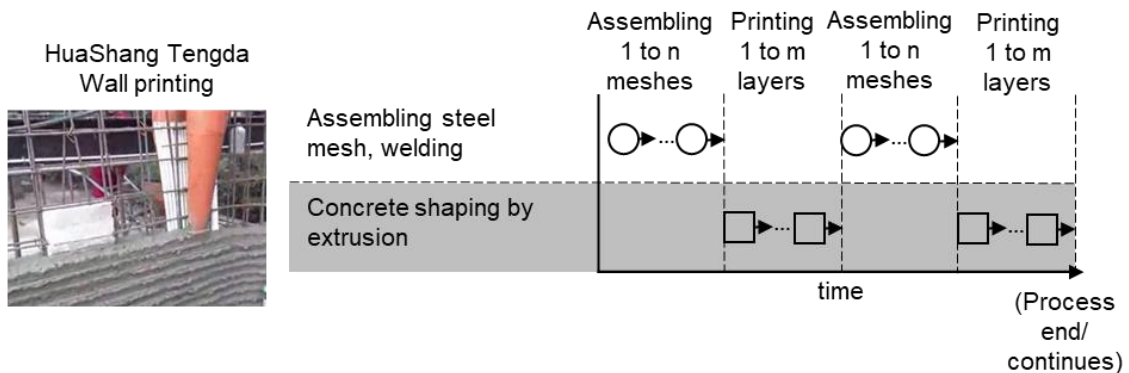
Example 2: Multi-step process



Example 3: Contiguous placement of reinforcement



Example 4: Placement of reinforcement prior to concrete shaping



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Figure 15. Examples for application of the new classification (Photo references: example 1 – [36], example 2 – [19], example 3 – [53], example 4 – [66]).

886 Example 4 presents a relatively rare case, where reinforcement is produced first in a distinct
887 process step by assembling steel mats and bars. This step is followed by progressing
888 encasement of reinforcement mats or cage with concrete in an additive extrusion-based
889 shaping process. Since the printhead dimensions limit the height of the reinforcing elements,
890 which can be encased in the approach under consideration, several repetitions of this
891 sequence, i.e., assembling reinforcement/concrete printing, are required before the product,
892 here an *in-situ* printed wall is finished. In this way Huashang Tengda fabricated a two-story
893 villa in Beijing. Note that in the given example the assembling of reinforcement was performed
894 in conventional manner, but this process step can be potentially automated and digitised as
895 well.

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897 5. Conclusions and outlook

898 The ongoing development of digital fabrication with concrete has led to an increasing number
899 of projects appearing in practice over the course of the past few years. With the aim of realising
900 structural applications, the need for reinforcement integration in DFC is obvious and thus, is
901 increasingly being addressed by industry and academia across the globe. Although the
902 functional requirements for reinforcement in DFC are similar to those in conventional concrete
903 construction, the particular process characteristics of DFC render traditional reinforcement
904 solutions unsuitable. As such, a new range of reinforcement solutions is being developed,
905 targeting specifically the integration in DFC, presented in various stages of development.

906 To facilitate comparison between solutions and indicate the performance and suitability of
907 each reinforcement method, a common language is desirable. To this end this paper presents
908 a classification framework for reinforcement in digital fabrication with concrete, focused on
909 additive digital concrete technologies.

910 First, the state of the art in reinforcement strategies for extrusion- and jetting-based 3D-
911 concrete-printing methods has been presented and discussed. The review, organised by
912 reinforcement type, and differentiated by material, presents various reinforcement concepts
913 including their advantages and limitations. The following potentials and research requirements
914 can be summarised from the review according to the reinforcement approaches:

- 915 • The application of straight or pre-bent reinforcement bars covers most of the structural
916 performance requirements but is challenging in terms of automation. In most of the
917 presented solutions, this type of reinforcement is still placed manually prior to concrete
918 shaping, or during in an alternating process. To address these issues, WAAM has been
919 proposed, although the alignment of the two AM processes is challenging.
- 920 • Alternatively, prefabricated grids and mats provide the desired reinforcement in two
921 directions, and can be applied either before concrete shaping, or afterwards. These
922 reinforcement solutions can provide a support to the fresh concrete during shaping,
923 but full automation has yet to be proven. The geometric freedom is moreover limited
924 by the geometry of standard mats, unless more advanced reinforcement fabrication
925 (e.g. Mesh Mould) is adopted.
- 926 • Pre-stressing 3D-printed elements provides continuous reinforcement along the entire
927 length of the object and has practically no limits in size or prestress force. This principle
928 obviously imposes additional process steps, which may be difficult to automate. In any
929 case, the location and shape of the pre-stress system should be incorporated in the
930 design process, for instance through the use of advanced optimization algorithms.
- 931 • The entrainment of cables, yarns, or meshes directly into or in between filaments
932 allows for a fully automated processes of both concrete shaping and reinforcement.
933 The common challenge in these methods is that they provide reinforcement mainly in

934 the printing direction, and thus, require additional attention in the direction
935 perpendicular to the printed layers.

- 936 • The dispersion of short fibres, premixed into the dry mortar, added during mixing, or
937 introduced just prior to deposition, allow for an excellent integration into the automated
938 printing process. First results on fibre reinforced mixtures, including SHCC's, are
939 promising although a strong fibre alignment may occur. Moreover, fibres generally do
940 not cross the filament interfaces.
- 941 • To provide reinforcement in the interlayer direction, penetration reinforcement
942 strategies may provide a solution. Although presented examples are still based on
943 manual application, these solutions have the potential to be automated. The main
944 challenge for penetration reinforcement is to acquire sufficient bond across layers.

945 The review provides the basis for the process classification framework for integration of
946 reinforcement into DFC technologies. As such, it connects with a previous publication in which
947 DFC technologies themselves have been classified. Firstly, a distinction is made between
948 process type, i.e., a pre-process, a single step process or a two-step process.

- 949 • For pre-process applications, reinforcement is typically integrated *during mixing*. This
950 concerns mainly short fibres, added into the ready mix or during dry mixing of the
951 printable composition.
- 952 • In single-step processes, reinforcement is integrated *during concrete shaping*. Here,
953 reinforcement is either entrained simultaneously with concrete, or placed between or
954 across layers. For single-step processes, a wide variety of reinforcement types is
955 available, spanning from bars and meshes to cables and yarns.
- 956 • Finally, for two-step processes a distinction can be made between reinforcement
957 placed *prior to concrete shaping* and *after concrete shaping*. In the first case, the
958 reinforcement solution can provide a support to the fresh concrete. In the latter, the
959 reinforcement is placed in or on the hardened concrete member or used to assemble
960 multiple parts into a reinforced structure.

961 To support the ongoing growth of DFC and bring applications beyond merely showcase
962 character, reinforcement strategies will have to be addressed. The classification framework
963 presented in this manuscript provides the means effectively to compare solutions and can
964 form a basis for further development and standardization in this rapidly expanding field.

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